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5 TITLE

IMAGE FORMING APPARATUS WITH IMPROVED
CAPABILITY OF IMAGE SUPERPOSITION

BACKGROUND

10 Field

 This patent specification relates generally to image forming apparatuses, and more specifically to the apparatus provided with a plurality of visible image forming units each including development means for developing to visualize latent
15 images held on latent image bearing members, and a light scanning means for forming the latent images through light beam scanning to be held onto the latent image bearing members of the visible image forming units.

20 Discussion of the Background

 A number of apparatuses are known capable of forming images by creating images to be rendered visible on a latent image bearing member such as photoreceptor and by transferring onto an intermediate transfer member to be superimposed as a
25 resultant images. Such apparatus may be exemplified by including only one visible image forming means comprising the latent image bearing member and plural developing units

associated therewith.

In order to form proper superposed images by such an image forming apparatus, in general, the surface of intermediate transfer member has to be rotated repeatedly as many times as
5 the number of image superposition.

As an example, in order to form a full-color image by superposing four visible images in the colors of yellow, magenta, cyan, and black (hereinafter referred to as Y, M, C, and K, respectively), Y image is first obtained by developing a latent
10 image held on a developing means in use for Y color, and subsequently transferred onto the intermediate transfer member during a first round of its rotation.

Thereafter, M, C, and K images created on respective latent image bearing members are transferred sequentially onto
15 intermediate transfer member during second, third, and fourth rounds of the rotation respectively, and a full-color image is finally obtained.

The latent image bearing member serves to hold a latent image generated by light beam scanning. The light beam
20 scanning, in turn, is divided broadly into two, one in the direction of surface displacement of the latent image bearing member (i.e., vertical scanning direction) and the other the direction perpendicular thereto (main scanning direction).

The scanning in the main scanning direction is carried out
25 with light beams repeatedly deflected to be scanned with an extremely short period along that direction by deflecting means including a rotating polygonal mirror and so on.

It is noted whether or no a light beam is located at a write initiation point is determined based on a beam detection signal which is output by a beam detection means provided to detect the beam at a predetermined location in the main scanning direction.

The timing for initiating light scanning, however, has to be determined after considering the location not only in the main scanning direction but also in the vertical scanning direction.

Therefore, the write initiation point in the vertical scanning direction is suitably determined by utilizing a mark detection signal output by a mark beam detection means for detecting a base mark which is affixed at a predetermined location in the direction of surface displacement of the intermediate transfer member.

To be more specific, the timing for initiating light scanning with respect to both the main and vertical scanning directions is adjusted by initiating the scanning based on the beam detection signal detected immediately after the generation of the mark beam detection signal.

In the light beam scanning carried out repeatedly along each rotation of the intermediate transfer member, however, shift in proper timing (or phase) of the scanning in the main scanning direction cannot sufficiently be avoided in general.

For example, assumed herein are a circumferential length of 600 mm and a linear speed of 40 mm/sec for the intermediate transfer member, and a scanning speed of 1000 time/sec in the main scanning direction for the light scanning means (which

gives rise to 15000 for the number of beam scanning during one round of the transfer member rotation).

Also assumed that the light beam happens to be located at a write initiation point at the moment when a mark is detected.

5 In this case, light beam scanning for the first round of rotation can be initiated at the noted moment of the mark detection.

In addition, the scanning continues in principle such that the light beam is located again at the write initiation point after the first round of rotation and that light beam scanning during
10 the second round of the rotation (i.e., the fifteen thousand and first round of the main direction beam scanning) is then initiated.

In practice, however, this is not the case since the location of light beam in the main scanning direction is shifted away
15 from the write initiation point when the first round of transfer member rotation is completed, because of an error in the circumferential length, and change in linear speed of intermediate transfer member. As a result, the difficulties arise as evidenced by the shift in phase of the scanning in the
20 main scanning direction, as described earlier.

This shift brings about a change in the period between the mark detection and the initiation of light scanning based on the succeeding beam detection, thereby resulting in shear in superposed visible images (color shift in multiple-color images)
25 in the vertical scanning direction.

In addition, a minute slippage may arise in a belt on driving roller in the case where a belt is used as an intermediate

transfer means. In this case, the shift may arise with more ease in phase of the scanning in the main scanning direction each round of rotation compared with an intermediate transfer drum with less possibility of slippage.

5 Furthermore, although the case has been described above in which the scanning is carried out such that the light beam is located again at the write initiation point after the first round of rotation (or the number of repeated beam scanning is integer), other cases may also arise with a non-integer.

10 For example, if the abovementioned linear speed of the intermediate transfer member is altered to 42 mm/sec from the previous value of 40 mm/sec, the number of repeated beam scanning during one round of rotation is obtained as 14285.7. In this case, therefore, the shift in phase of light beam scanning
15 in the main scanning direction is brought about regardless of the noted error in the circumferential length or a change in linear speed of intermediate transfer member.

As an image forming apparatus capable of alleviating the shear in superposed visible images caused by the noted shift in
20 phase during the main direction scanning, an apparatus has been disclosed in Japanese Laid-Open Patent Application No. 10-202944.

This apparatus is adapted to control a polygon motor as the driving power source for a rotating polygonal mirror so as to
25 adjust the phase of the rotation of polygonal mirror as a part of deflecting means to coincide with the signal output itop based on the difference in time between the signal itop and a signal BD.

The signals itop and BD designate herein the mark detection, and the beam detection signals, respectively, as noted earlier.

By initiating light scanning for each round of the rotation of intermediate transfer drum with the apparatus, the shift in
5 the phase of beam scanning can be resolved to a certain extent and the shear in superposed visible images due to the noted shift in phase during the main direction scanning can be suppressed effectively.

In order to form superposed images by such apparatuses,
10 however, the surface of intermediate transfer member has to be rotated as many times as the number of image superposition, that is three times of the rotation for a triple-color image, for example. This comes to result a prolonged period of time of image formation compared with the case of mono-color images
15 which is carried out without image superposition.

On the other hand, another type of image forming apparatus for obtaining superposed images is also known previously, which is provided with as many visible image forming means as the number of the superposition each
20 including a latent image bearing member and a developing means accompanied thereto.

For forming full-color images, for example, the noted apparatus is provided with four visible image forming means each in use for forming images of four colors Y, M, C, and K,
25 respectively.

In this structure of the image forming apparatus, the superposition repeated as many times as required can be carried

out during one or less round of the rotation of intermediate transfer means instead of rotating as many times as described earlier, and the aforementioned difficulty such as prolonged image forming period can be obviated, which is otherwise caused from rotating as many times as the number of image superposition.

This apparatus, however, may suffer from the shear in superposed visible images in the vertical scanning direction, when any phase shift is once caused among the plural visible image forming means in the main scanning direction.

As an image forming apparatus capable of alleviating such shear in superposed visible images in the vertical scanning direction, an apparatus has been disclosed in Japanese Laid-Open Patent Application No. 2000-94747.

This apparatus is adapted to perform light beam scanning using polygonal mirrors for exclusive use onto respective latent image bearing members of visible image forming means. In addition, each of the polygonal mirrors is provided with plural beam detection means corresponding thereto. Based on beam detection signals from the beam detection means, phase of the rotation of polygonal mirrors is controlled so as to synchronize the phase for respective mirrors.

By bringing through such synchronization the phase shift to coincide with each other among the plural visible image forming means in the main scanning direction, the shear of superposed images can be alleviated in the vertical scanning direction.

In such image forming apparatuses, however, a drawback arises in which the structure of light beam scanning means becomes unduly complicated by incorporating rotating polygonal mirrors, polygon motor, and motor control circuit and so on, for
5 exclusive use for each visible image forming means.

SUMMARY

Accordingly, it is an object of the present disclosure to provide an image forming apparatus, having most, if not all, of
10 the advantages and features of similar employed methods and systems, while eliminating many of the aforementioned disadvantages.

It is another object of the invention to provide an image forming apparatus capable of obviating several difficulties such
15 as the shear of superposed images in the vertical scanning direction, prolonged image forming periods resulted from rotating an intermediate transfer member as many times as the number of image superposition, and undue complication in the structure of light beam scanning means caused by incorporating
20 plural light deflecting means for exclusive use for each visible image forming units.

The following description is a synopsis of only selected features and attributes of the present disclosure. A more complete description thereof is found below in the section
25 entitled "Description of the Preferred Embodiments"

To achieve the foregoing and other objects, an image

forming apparatus is provided including

a plurality of latent image bearing members;

a plurality of visible image forming units each including
development means for developing latent images on the latent
5 image bearing member to form visible images thereon;

a light scanning means for forming the latent images on
the latent image bearing members, the scanning means including
a deflecting means, to form latent images on surfaces of the
latent image bearing members;

10 an endless intermediate transfer member;

means for rotating the endless intermediate transfer
member;

a transfer means for transferring visible images formed by
visible image forming units in a manner to be superposed on the
15 endless intermediate transfer member;

a mark detection means for detecting a base mark affixed
onto a predetermined location on the surface of the endless
intermediate transfer member to provide a mark detecting signal
corresponding thereto;

20 a standard angle detection means for detecting light
deflected by the deflecting means arriving at a predetermined
angle of deflection; and

a deflection angle phase correction means included in the
light scanning means for correcting the phase of change in angle
25 of deflection caused by the deflecting means based at least on
the mark detection signal from mark detection means and

a standard angle detection signal from standard angle

detection means.

In the present image forming apparatus, the light scanning means is configured to carry out light scanning onto the plurality of latent image bearing members such that at least one pair of neighboring visible image forming units of the plurality of visible image forming units are both subjected to light scanning by a same of deflecting means, and the endless intermediate transfer member is adapted to be displaced for a plurality of rounds of rotation such that the surface of the endless transfer member is superposed thereon with plural visible images each provided by the same of the visible image forming units during each round of rotation.

According to another aspect, the plurality of visible image forming units in the image forming apparatus each includes first and second image forming units to constitute a pair of neighboring visible image forming units, such that, after forming a double-color image by sequentially transferring to superpose plural visible images each formed by the first and second visible image forming units onto the surface of the endless intermediate transfer member during a first round of rotation of the endless intermediate transfer member, a quadruple-color image is formed by sequentially transferring to superpose plural visible images each formed by the first and second visible image forming units onto the double-color image during the second round of the endless rotation of the endless intermediate transfer member.

In addition, the light scanning means is configured, after

storing a time lag $dt1$ as a difference between the time Ta when a mark detection signal is detected and the time Tb when the standard angle detection signal is detected during a first rotation of the endless intermediate transfer member,

5 to measure the time lag $dt2$ as the difference between the time Tc when the mark detection signal is detected and the time Td when the standard angle detection signal is detected during the second rotation of intermediate transfer member, and
 to correct the phase based on time lag $dt2$ and time lag $dt1$
10 previously stored.

 According to still another aspect, the light scanning means included in the image forming apparatus is configured to
 store in advance a predetermined base correction time $t1'$;
15 initiate optical image writing for a first round of rotation of the endless intermediate transfer member onto the latent image bearing member included in the first visible image forming unit based on a standard angle detection signal detected after time Te determined as the time elapsed by base correction
20 time $t1$ from time Ta ;

 correct the phase, during a period between time Tc and the time including time Tc elapsed by base correction time $t1$, based on time lag $dt2$ and time lag $dt1$; and

 initiate optical image writing for a second round of
25 rotation of the endless intermediate transfer member onto the latent image bearing member included in the first visible image forming unit.

According to another aspect, the light scanning means is configured to store in advance a predetermined standard time difference t_s , to compute a time difference Δt as the difference
5 between time lag dt_2 and time lag dt_1 , and, in a case where
(standard time difference t_s) \geq (time difference Δt), not to
correct the phase prior to optical image writing for a first round
of rotation of intermediate transfer member onto the latent
image bearing member included in the first visible image
10 forming unit.

According to another aspect, in the case where it is decided that the correction of the phase is not to be implemented, the light scanning means is configured to
15 initiate optical image writing for a second round of
rotation of the endless intermediate transfer member onto the
latent image bearing member included in the first visible image
forming unit based on the time when the standard angle
detection signal is detected firstly after a time that has elapsed
20 by a predetermined time from T_c , and

determine the predetermined time in comparison with the
base correction time t_1 based in at least time T_f when optical
image writing is initiated for a first round of rotation of the
endless intermediate transfer member onto the latent image
25 bearing member included in the first visible image forming unit,
time T_e , base correction time t_1 , the time lags dt_1 and dt_2 .

The process for determining time parameters such as the

noted T_e , T_f , t_1 , dt_1 , dt_2 and others will be detailed herein below according to process requirements for image formation.

The image forming apparatus disclosed herein can offer several advantages over similar apparatuses previously known.

5 For example, the first and second process units included in the image forming apparatus constitute a pair neighboring with each other, each comprising two visible image forming means which are each in the relationship neighboring with each other.

10 In this apparatus, after forming a double-color image by sequentially transferring to superpose Y and M toner images each formed by the first and second process units onto the surface of the endless intermediate transfer member during a first round of rotation of the endless transfer member, a quadruple-color image is formed by sequentially transferring to
15 superpose C and K toner images each formed by the first and second process units onto the double-color image during the second round of rotation of the endless intermediate transfer member.

20 In addition, the light scanning means 20 is configured, after storing the time lag dt_1 during a first rotation of the endless intermediate transfer member, to measure the time lag dt_2 during the second rotation of the endless intermediate transfer, and to correct the phase based on time lag dt_2 and time lag dt_1 previously stored.

25 As a result of the noted structure of the image forming apparatus, by correcting the phase of rotation in the main direction scanning during each round of the rotation based on

time lags dt_1 and dt_2 , the disagreement in images through quadruple superposition can be obviated.

Utilizing this image forming apparatus with the suitably determined time parameters such as T_e , T_f , t_1 , dt_1 , and dt_2 ,
5 several difficulties encountered with the known similar apparatuses can now be obviated.

That is, there obviated with the present apparatus are the shear of superposed images in the vertical scanning direction, prolonged image forming periods resulted from a large number of
10 rotation of intermediate transfer member, and undue complication in the structure of light beam scanning means caused by incorporating plural light deflecting means for exclusive use for each visible image forming units.

15 The present disclosure and features and advantages thereof will be more readily apparent from the following detailed description and appended claims when taken with drawings.

BRIEF DESCRIPTION OF THE DRAWINGS

20 In the following drawings, like references numerals will be used to refer to like elements in the various drawings, in which:

FIG. 1 is a diagrammatic schematic view illustrating the basic structure of a printer according to one embodiment disclosed herein;

25 FIG. 2 is an enlarged view illustrating several units included in the printer such a light scanning means, two process units, and intermediate transfer means;

FIG. 3 is an enlarged view illustrating the light scanning means included in the printer;

FIG. 4 is a diagrammatic block diagram illustrating portions of circuit construction of the printer disclosed herein;

5 FIG. 5 includes a timing chart illustrating the generation and sequence of several signals in the printer disclosed herein;

FIG. 6 includes a timing chart illustrating the sequence of several signals in the case where the expressions "time lag $dt_1 < \text{time lag } dt_2$ " and "time difference $tx < \text{time difference } ty$ " both
10 hold;

FIG. 7 includes a timing chart illustrating the sequence of signals in the case where the expressions "time lag $dt_1 < \text{time lag } dt_2$ " and "time difference $tx > \text{time difference } ty$ " both hold;

FIG. 8 includes a timing chart illustrating the sequence of
15 signals in the case where the expressions "time lag $dt_1 > \text{time lag } dt_2$ " and "time difference $tx > \text{time difference } ty$ " both hold;

FIG. 9 includes a timing chart illustrating the sequence of signals in the case where the expressions "time lag $dt_1 > \text{time lag } dt_2$ " and "time difference $tx < \text{time difference } ty$ " both hold;
20 and

FIG. 10 includes a timing chart illustrating the sequence of signals during the operation for obviating the disagreement in image superposition in the case where a relatively large change arises in the speed of the intermediate transfer belt caused by
25 belt slippage between the neighboring photoreceptors.

of signals during the operation for obviating the disagreement in image superposition in the case where a relatively large change arises in the speed of the intermediate transfer belt caused by belt slippage between the neighboring photoreceptors.

5

DESCRIPTION OF THE PREFERRED EMBODIMENTS

In the detailed description which follows, specific embodiments of an image forming apparatus and light scanning means incorporated into the apparatus are primarily described.

10 It is understood, however, that the present disclosure is not limited to these embodiments. For example, it is appreciated that improved combination of the photoreceptor units and the light scanning means may also be adaptable to any form of image forming apparatus. Other embodiments will be
15 apparent to those skilled in the art upon reading the following description.

In the present disclosure, an image forming apparatus is provided including at least a plurality of visible image forming
20 units each including development means for developing to visualize latent images held on latent image bearing members; light scanning means for forming the latent image by deflecting light, emanated according to image information, by means of a deflecting means, to irradiate displacing surfaces of latent image
25 bearing members; an intermediate transfer member provided with a endlessly displacing surface; a transfer means for transferring visible images formed by visible image forming

means to be superposed thereon; a mark detection means for detecting a base mark affixed onto a predetermined location on the surface of intermediate transfer member; a standard angle detection means for detecting light deflected by the light scanning means arriving at a predetermined angle of deflection; and a deflection angle phase correction means included in the light scanning means for correcting the phase of change in angle of deflection caused by light scanning means based at least on a mark detection signal from mark detection means and a standard angle detection signal from standard angle detection means.

In the present image forming apparatus, the light scanning means is configured to carry out light scanning onto the plurality of latent image bearing members such that at least one pair of neighboring visible image forming units of the plurality of visible image forming units are subjected to light scanning both by a same of deflecting means, and the intermediate transfer member is adapted to be displaced for a plurality of rounds such that the surface of the transfer member is superposed thereon with plural visible images each provided by the same of the visible image forming units during each round.

In another aspect of the present disclosure, the plurality of visible image forming units in the image forming apparatus each includes first and second image forming units to constitute a pair of neighboring visible image forming units, such that, after forming a double-color image by sequentially transferring to superpose plural visible images each formed by the first and

second visible image forming units onto the surface of intermediate transfer member during a first round of rotation of intermediate transfer member, a quadruple-color image is formed by sequentially transferring to superpose plural visible
5 images each formed by the first and second visible image forming units onto the double-color image during the second round of rotation of intermediate transfer member.

In addition, the light scanning means is configured, after storing a time lag $dt1$ as a difference between the time Ta when
10 a mark detection signal is detected and the time Tb when the standard angle detection signal is detected during a first rotation of intermediate transfer member, to measure the time lag $dt2$ as the difference between the time Tc when the mark detection signal is detected and the time Td when the standard
15 angle detection signal is detected during the second rotation of intermediate transfer member, and to correct the phase based on time lag $dt2$ and time lag $dt1$ previously stored.

In still another aspect of the present disclosure, the light scanning means included in the image forming apparatus is
20 configured to store in advance a predetermined base correction time $t1'$; initiate optical image writing for a first round of rotation of intermediate transfer member onto the latent image bearing member included in the first visible image forming unit based on a standard angle detection signal detected after time
25 Te as the time elapsed by base correction time $t1$ from Ta ; correct the phase, during a period between time Tc and the time Tc elapsed by base correction time $t1$, based on time lag $dt2$ and

time lag $dt1$; and initiate optical image writing for a second round of rotation of intermediate transfer member onto the latent image bearing member included in the first visible image forming unit.

5 In another aspect of the present disclosure, the light scanning means is configured to store in advance a predetermined standard time difference ts ; to compute a time difference Δt as the difference between time lag $dt2$ and time lag $dt1$; and, in a case where (standard time difference ts) \geq (time
10 difference Δt), not to correct the phase prior to optical image writing for a first round of rotation of intermediate transfer member onto the latent image bearing member included in the first visible image forming unit.

 In the case where it is decided that the correction of the
15 phase is not implemented, the light scanning means is configured to initiate optical image writing for a second round of rotation of intermediate transfer member onto the latent image bearing member included in the first visible image forming unit based on the time when the standard angle detection signal is
20 detected firstly after a time elapsed by a predetermined time from Tc , and determine the predetermined time in comparison with the base correction time $t1$ based on at least time Tf when optical image writing is initiated for a first round of rotation of intermediate transfer member onto the latent image bearing
25 member included in the first visible image forming unit, time Te , base correction time $t1$, the time lags $dt1$ and $dt2$.

 Also, in the case where it is decided that correction of the

phase is not implemented, the light scanning means is configured to store in advance the time difference t_x between the time T_e and the time T_f , and determine the predetermined time based on at least magnitude relation of the time lags dt_1 and dt_2 ,
5 and the time difference t_x .

Alternatively, also in the case where it is decided that correction of the phase is not implemented, the light scanning means is configured to store the sum of the time difference t_x and the base correction time t_1 as an added correction time t_1' ,
10 and determine the predetermined time based on at least magnitude relation of the time lags dt_1 and lag dt_2 , and the added correction time t_1' .

In another aspect, the image forming apparatus disclosed herein further includes a plurality of base marks equally spaced
15 with a predetermined pitch there between each affixed onto the intermediate transfer belt member in the direction of endless rotation, in which, in the case where optical image writing for a first round of rotation of the intermediate transfer member onto the latent image bearing member included in the first visible
20 image forming unit is completed at the time T_g when a predetermined number of the mark detection signals are detected after the time T_a ,

the light scanning means is configured to correct the phase, during the period between the time T_g and the time after time
25 T_g elapsed by the base correction time t_1 , based on the time lag dt_3 between time T_g and the time when the standard angle detection signal is detected firstly after time T_g , and the time

lag dt_1 ; and to initiate optical image writing for the first round of rotation of intermediate transfer member onto the latent image bearing member included in the second visible image forming unit.

5 In the case where optical image writing for a second round of rotation of intermediate transfer member onto the latent image bearing member included in the first visible image forming unit is already completed at the time T_h when anyone of the mark detection signals is detected after the time T_c ,

10 the light scanning means is configured to correct the phase, during the period between the time T_h and the time after time T_h elapsed by the base correction time t_1 , based on the time lag dt_4 between the time T_h and the time when the standard angle detection signal is detected firstly after the time T_h , and the
15 time lag dt_2 ; and initiate optical image writing for the second round of rotation of intermediate transfer member onto the latent image bearing member included in the second visible image forming unit.

 In another aspect, the image forming apparatus disclosed
20 herein further includes a first mark detection means as the mark detection means, and a second mark detection means for detecting the base mark situated between first and second visible image forming units, in which, in the case where optical image writing for a first round of rotation of intermediate
25 transfer member onto latent image bearing member included in the first visible image forming unit is already completed at the time T_i when a mark detection signal is detected by the second

mark detection means after the time T_a when a previous mark detection signal is detected by the first mark detection means,

the light scanning means is configured to correct the phase, during the period between the time T_i and the time after time T_i elapsed by the base correction time t_1 , based on the time lag dt_5 between the time T_i and the time when the standard angle detection signal is detected firstly after time T_i , and the time lag dt_1 ; and initiate optical image writing for the first round of rotation of intermediate transfer member onto the latent image bearing member included in the second visible image forming unit.

In the case where optical image writing for the second round of rotation of intermediate transfer member onto latent image bearing member included in the first visible image forming unit is already completed at the time T_j when a mark detection signal is detected by the second mark detection means after the time T_c when a previous mark detection signal is detected by the first mark detection means,

the light scanning means is configured to correct the phase, during the period between the time T_j and the time after time T_j elapsed by the base correction time t_1 , based on the time lag dt_6 between the time T_j and the time when the standard angle detection signal is detected firstly after time T_j , and the time lag dt_2 ; and initiate optical image writing for the second round of rotation of intermediate transfer member onto the latent image bearing member included in the second visible image forming unit.

In another aspect, the light scanning means included in the image forming apparatus is configured, in the case where the image information is of double-color images which are formed by superposing first color images formed by the first visible image forming unit and second color images formed by the second visible image forming unit, to initiate optical image writing onto latent image bearing member included in the first visible image forming unit based on the time when the standard angle detection signal is detected firstly after the time T_a without waiting for the arrival of the time T_e .

In addition, the image forming apparatus further includes a plurality of development means included in each of the first and second visible image forming units, and a development effecting means for selectively enabling one of the first and second visible image forming units, in which, in the case where the double-color images can be formed of the first color which can be developed anyone of the plurality of development means included in the first visible image forming unit and of the second color which can be developed anyone of the plurality of development means included in the second visible image forming unit,

the first and second visible image forming units are each configured to enable the first color and the second color by selectively enabling one of the plurality of development means included in each of the first and second process units, respectively, by the development effecting means.

The above noted features of the image forming apparatus and light scanning means incorporated into the apparatus have been materialized through the findings and efforts by the present inventors toward acquiring and improving these features,
5 which follows.

By way of example, the image forming apparatus described earlier is adapted to perform light beam scanning using polygonal mirrors for exclusive use onto respective latent image bearing members of visible image forming means. In addition,
10 each of the polygonal mirrors is provided with plural beam detection means corresponding thereto.

With this construction of the image forming apparatus, the superposition repeated as many times as required can be carried out during one or fewer round of the rotation of intermediate
15 transfer means, and the image disagreement during superposition along the repeated rotation of intermediate transfer means can be obviated.

However, another drawback may arise in contrast such as the phase shift in the main scanning direction among the plural
20 visible image forming means and the shear of superposed images in the vertical scanning direction caused by the change in the speed of the surface of intermediate transfer belt.

If light beam scanning is carried out for plural latent image bearing members by means of one single light deflecting
25 means, the shear of superposed images in the vertical scanning direction can be obviated, since the phase in the main scanning direction among the plural visible image forming means is

synchronized as long as no change in the speed of the surface of intermediate transfer belt is present.

It is quite difficult, however, to prevent in practice the change in the speed of the surface of intermediate transfer belt.

5 In the noted image forming apparatus, in particular, it is common to utilize a belt as the intermediate transfer means in order to fulfill the layout designing requirements such that all of the photoreceptor units are positioned being opposed to the surface of the intermediate transfer means, while the apparatus
10 is designed in its size reduced as much as possible.

Since this intermediate transfer belt may be suffered from slippage on the drive roller with more ease compared with an intermediate transfer drum, this may arise the change in the speed of the surface of intermediate transfer belt.

15

The present inventors then have found in the case where four process units for Y, M, C, and K images are provided the disagreement in the position of toner image transfer may take place more often between a first color and a fourth color, which
20 are positioned most distant among the four units. In contrast, the disagreement can be suppressed more between most neighboring pairs of the units such as, for example, a first color and a second color.

This is considered due to the fact that, in the neighboring
25 pair formed of two photoreceptors adjacent with each other, the change in the speed of the surface of intermediate transfer belt between the two rarely takes place, or may take place with small

speed change, if any, because of the short distance between the two photoreceptors.

In the present disclosure, therefore, the disagreement in the position of toner image transfer in the main direction scanning can effectively be suppressed by using one single
5 deflecting means for at least one neighboring pair, and by bringing into coincidence the phase in that direction between the two visible image forming means.

In addition, the present structure facilitates to obviate
10 more complicated structure of the light scanning means otherwise required with plural deflecting means each for exclusive use.

Furthermore, the superposing image transfer is carried out not during one or less round of surface displacement of
15 intermediate transfer means, still resulting in the number rotation less than that of superposition. This is because image superposition by the plural visible image forming means is carried out in addition to that by the surface displacement.

In the case of forming a full-color image, for example,
20 after forming a double-color image by sequentially transferring to superpose Y and M toner images each formed by the first and second process units onto the surface of intermediate transfer belt during a first round of rotation of the transfer belt, a quadruple-color image is formed by sequentially transferring to
25 superpose C and K toner images each formed by the first and second process units onto the double-color image during the second round of rotation of intermediate transfer belt. As a

result, an increase in printing time can be avoided, which is otherwise required for repeated rotations of as many times as the number of images transferred.

5 Still in addition, through correcting the phase of the change in beam deflection angle by means of deflection angle phase correction means based on mark detection, and beam detection signals, undue mismatch in image superposition can also be prevented, which is caused by the shift in the phase in the main scanning direction along the rounds of belt rotation.

10 As a result, the difficulties described earlier can be obviated, by the image forming apparatus disclosed herein, such as the shear of superposed images in the vertical scanning direction, prolonged image forming periods resulted from rotating an intermediate transfer member as many times as the
15 number of image superposition, and undue complication in the structure of light beam scanning means caused by incorporating plural light deflecting means for exclusive use for each visible image forming units.

20 As an exemplary embodiment of image forming apparatus according to the present invention, a printer of the electrophotographic type will be described herein below.

FIG. 1 is a diagrammatic schematic view illustrating the basic structure of the printer.

25 Referring to FIG. 1, this printer includes at least a first process unit 10YC for forming Y and T toner images, and a second process unit 10MK for forming M and K toner images. It

may be added according to conventional notation that the signs Y, M, C, and K designate four color members of, yellow, magenta, cyan, and black, respectively (which will be used throughout the following description).

5 In addition to the two process units as visible image forming means (10YC and 10MK), the printer further includes a light scanning means 20, an intermediate transfer means 30, and a sheet cassette 40 as sheet feeding means. Also included as conveyor means are a conveyor roller pair 41, a registration
10 roller pair 42, a secondary transfer bias roller 43, and a fixing means 44.

 The first process unit 10YC includes at least a photoreceptor unit 1YC as latent image bearing member, a charging means 2YC, two developing means 3Y and 3C, a
15 cleaning means 4YC, and a discharging means (not shown). In addition, the unit 10YC also includes a development effecting means (not shown) for enabling the operation of either one of the two developing means 3Y and 3C by selectively displacing with respect to the photoreceptor unit 1YC.

20 Since the second process unit 10MK has the structure similar to the first process unit 10YC, its detailed description is abbreviated herein.

 The charging means 2YC included in the first process unit 10YC is adapted to uniformly charge the surface of the
25 photoreceptor 1YC through rubbing and contact with a charging roller.

 Onto thus charged surface of the photoreceptor 1YC, laser

light beams are scanned, which are modulated and deflected by the light scanning means 20. Electrostatic latent images for Y or C image are now formed on the charged surface of the photoreceptor 1YC.

5 The thus formed latent images are subsequently subjected to the development process for forming visible images such as either Y toner image by developing means 3Y or C toner images by the means 3C.

Incidentally, other type of the charging means may
10 alternatively be utilized such as by a charger or a brush in place of the noted charging roller.

The developing means 3Y and 3C includes Y and C developing agents, respectively, which consist of magnetizable developer mix including magnetic carrier granules and, Y and C
15 toner particles.

In addition, the developing means 3Y and 3C are further provided with a developing roller, which is positioned being exposed partially from an opening of a developer case, a stir means for stirring the Y and C developing agents, toner
20 concentration sensors (which is hereinafter referred to as T sensors) and so on.

Being transported to the developing roller while stirring by the stir means, Y and C toners in the developing agents are each friction-charged, and subsequently held onto the face of
25 developing roller.

The Y and C toners are each controlled in its layer thickness on the developing roller by a control means (not

shown), brought to developing regions corresponding to the photoreceptor 1YC, and then held onto the electrostatic latent images. Y or C toner images are thus created on the photoreceptor 1YC.

5 The Y and C developing agents are each brought back by the rotating developing roller to the container of developing means 3Y and 3C with decreased concentration of Y and C toners resulted from the consumption during toner image development process.

10 The T sensors are each provided with magnetic permeability sensors which are configured to output voltages according to magnetic permeability of the Y and C developing agents, which are transported while stirring by the stir means as noted earlier. The magnetic permeability is correlated to the
15 toner concentration to a certain extent. Therefore, the T sensors are operative of outputting voltages according to Y and C toner concentration in the developing agents.

 The values of the output voltages are then sent to a replenish control unit (not shown). The replenish control unit,
20 in turn, is provided with RAM as a memory unit which is configured to store several data as target output voltages, V_{tref} , for the Y and C toners.

 In addition, the replenish control unit is configured also to store further data of V_{tref} for the M and K toners included in the
25 second process unit 10MK.

 As an example, the V_{tref} for Y toner is then utilized for controlling the drive of Y toner dispensing unit (not shown). To

be concrete, the noted replenish control unit is adapted to drive and control the Y toner dispensing unit for replenishing Y toner particles into the developing means 3Y such that voltage values output from the sensor for Y toner are brought to coincide with, or to be close as much as possible to, the noted output voltage V_{tref} for the Y toner.

The replenishing step for the Y toner thus facilitates to maintain the concentration of Y toners within a predetermined range. In a similar manner, the concentration is properly adjusted and maintained for other M, C, and K developing agents as well.

The Y and M toner images formed on the photoreceptor 1YC are then subjected to intermediate transfer onto an intermediate transfer belt 31 which will be described later on. The surface of the photoreceptor 1YC following the intermediate transfer is cleaned by removing residual toners by the cleaning means 4YC, and discharged by irradiating light emanated from a discharging lamp.

Thereafter, the surface of the photoreceptor 1YC is uniformly charged by the charging means 2YC and prepared for the next image forming step.

The intermediate transfer means 30 is provided with an intermediate transfer belt 31, a drive roller 32, a driven roller 33, first and second intermediate transfer chargers 34 and 35, and a belt cleaning means 36.

The intermediate transfer belt 31, as an endless belt being suspended and tension wound, is adapted to be driven to rotate

counterclockwise as shown in the drawing by a drive system (not shown). The first and second intermediate transfer chargers 34 and 35 are positioned on the inner periphery of intermediate transfer belt 31 so as to oppose to the first and second process units 10YC and 10MK, respectively, with the belt 31 interposed there between.

This opposing positional relationship between the transfer chargers 34 and 35, and process units 10YC and 10MK, now forms first and second intermediate transfer positions, respectively.

In each of first and second intermediate transfer positions, an intermediate transfer electric field is generated by electrical charge transfer from the intermediate transfer chargers 34 and 35 to the intermediate transfer belt 31.

The Y toner images previously formed on the photoreceptor 1YC for Y, C images are subjected to intermediate transfer onto an intermediate transfer belt 31 under the influence of the intermediate transfer electric field.

Subsequently, M toner images separately formed on the photoreceptor 1MK for M, K images by the second process unit 10MK are subjected to intermediate transfer onto the thus formed Y toner images, whereby a sequential overlap of color toner images of Y and M toner images are formed.

Thereafter, the double-color toner images formed as the overlap of Y and M toner images are brought to coincide with (or brought back to) the position of the first intermediate transfer after approximately one circle along the endless rotation of the

intermediate transfer belt 31.

During the time for the double-color toner images be brought back, electrostatic latent images for forming C toner, which are previously formed on the photoreceptor 1YC for Y, C
5 images, are developed to form C toner images by the development means 3C for C images.

Subsequently, the C toner images are subjected to intermediate transfer to form another sequential overlap on top of the double-color toner images in the first intermediate
10 transfer position. As a result, triple-color toner images formed on the intermediate transfer belt 31.

In a similar manner, another toner images are further subjected to intermediate transfer to form a further sequential overlap on top of the triple-color toner images in the second
15 intermediate transfer position, whereby quadruple-color toner images are formed.

Thereafter, the quadruple-color toner images are collectively subjected to the secondary transfer onto a transfer paper P as a recording member at a secondary transfer nip,
20 which will be detailed later on.

Being combined with the white color of transfer paper P, a full-color pictorial image is now resulted from the quadruple-color toner images.

Residual toner particles, which are in existence on the
25 surface of intermediate transfer belt 31 following the passage through the secondary nip, are subsequently cleaned by a belt cleaning means 36 which is provided in contact with the portion

of the belt 31 supported from the behind by the driven roller 33.

Being situated under the light scanning means 20, a sheet feeding cassette 40 is provided for loading plural transfer paper sheet P stacked as a batch with an uppermost sheet thereof
5 being pressed against the sheet feeding roller 6a.

When the feeding roller 6a is driven to rotate at a predetermined timing, the uppermost transfer sheet is fed forward to a sheet feeding path.

A secondary transfer bias roller 43 is further provided to
10 be brought into pressed contact with the drive roller 32 included in the intermediate transfer means 30 with the intermediate transfer belt 31 interposed there between, whereby a secondary transfer nip is formed. To the secondary transfer bias roller 43, secondary transfer biases are applied by an electrical power
15 source (not shown).

The transfer sheet P forwarded from sheet feeding cassette 40 to sheet feeding path is fed through conveyor roller pair 41 and nipped by the registration roller pair 42.

On the other hand, the quadruple-color toner images
20 previously formed on the intermediate transfer belt 31 advance into the secondary transfer nip along the endless rotation of the intermediate transfer belt 31.

The registration roller pair 42 then operates to feed the transfer sheet P nipped therewith forward to the secondary
25 transfer nip in the timing suitable for bringing the sheet P in close contact with the quadruple-color toner images. As a result, the quadruple-color toner images are adhered closely to

transfer sheet P, and subjected to the secondary transfer onto the transfer sheet P under the influence of secondary transfer biases and nip pressure, to thereby form a full-color pictorial image.

5 The transfer paper sheet P with the thus formed full-color pictorial image is forwarded to the fixing means 44.

 The fixing means 44 is provided with a heated roller 44a and a pressing roller 44b, which are brought into contact with one another to form a fixing nip, in that the constituent rollers
10 are driven such that the surfaces thereof in combination can generate a resultant forwarding movement of the sheet paper through the nip.

 The fixing means 44 operates to have the forwarded paper sheet P nipped by the fixing nip and the full-color pictorial
15 image fixed onto the face of the transfer sheet. After the passage through the fixing means 44, the paper sheet P is discharged to the exterior of the apparatus.

 A base mark (not shown) is affixed onto a predetermined location of one of the circumferential edges of the intermediate
20 transfer belt 31. Corresponding to this base mark, a mark detection means 50 is provided, comprising a reflection type photosensor and being positioned over the intermediate transfer means 30 as shown in the drawing.

 Mark detection signals generated by the mark detection
25 means 50 are transmitted to a main controller (not shown). Based on the mark detection signals, there generated are optical writing initiation signals in the vertical scanning

direction to be directed to respective photoreceptors 1YC and 1MK included in the process units 10YC and 10MK, respectively.

It should be noted that the first and second process units 10YC and 10MK constitute a pair neighboring with each other, each comprising two visible image forming means which are each in the relationship neighboring with each other.

In addition, each of the process units is provided with a development shifting means, as the development effecting means noted earlier, capable of enabling (or disabling) the operation of either one of the two visible image forming means by selective displacement.

With such a construction as note just above of the process units, after the first process unit 10YC enabled the development means 3Y for Y images and carried out the Y development during the first round of the transfer belt, the development means 3C for C images performs C development during the second round.

Similarly, after the second process unit 10MK enabled the development means 3M for M images and carried out the M development during the first round of the transfer belt, the development means 3K for K images performs K development during the second round.

In the next place, characteristic features will be detailed on the printer disclosed herein.

FIG. 2 is an enlarged view illustrating several units included in the printer such as the light scanning means 20, two

process units 10YC and 10MK, and intermediate transfer means
30.

The light scanning means 20 includes at least two laser
diodes (not shown, which are hereinafter referred to as LDs) as
5 light sources, a polygonal unit 23 as a deflecting means, first
and second collimator lenses 24 and 25, and four reflecting
mirrors 26a, 26b, 26c, and 26.

In addition to polygonal mirrors 23a's, the polygonal unit
23 includes a polygon motor and a polygon motor controller (not
10 shown).

One of the LDs operates to emanate laser beams L1 after
modulated by a modulation means (not shown) according to Y
and C image information.

Being reflected by one of six deflecting faces of the mirror
15 23a, which is positioned just above the face deflecting the beams
L1, as shown in FIG. 2, the emanated laser beams L2 are
deflected successively in the main (or horizontal) scanning
direction as shown in FIG. 3.

Subsequently, as shown in FIG. 2, the beams L1 are
20 collimated through the first collimator lens 24, and then
reflected successively by the first and second reflecting mirrors
26a and 26b.

Furthermore, after collimated through the second collimator
lens 25 and reflected by the reflecting mirror 26c, the beams L1
25 are scanned in the horizontal scanning direction over the surface
area of the photoreceptor 1YC of first process unit 10YC.

Every time the deflecting (and reflecting) face reflecting

laser beams is switched from one to another with the rotation of polygonal unit 23, the beams L1 are adapted to be scanned once in the horizontal scanning direction over the surface area.

In addition, every moment when the laser beams L1 are
5 reflected to a predetermined direction during each scanning, the beams are detected by a first beam detection means 5YC, as the base mark detection means, provided on a side of the photoreceptor 1YC.

The light scanning in the vertical scanning direction is
10 carried out with the displacement of the surface of photoreceptor 1YC in that direction. And, the first beam detection means 5YC is adapted to output a first beam detection signal every time the beams are detected.

The other LD operates to emanate laser beams L2 after
15 modulated by the modulation means (not shown) according to M or K image information. Being reflected by one of six deflecting faces of the rotating polygonal mirror 23a, as a regular hexagonal prism, the emanated laser beams L1 are deflected successively in the horizontal scanning direction as shown in
20 FIG. 3.

Subsequently, the beams L2 are collimated through the first collimator lens 24, reflected successively by the fourth and fifth reflecting mirrors 26d and 26e, and scanned in the horizontal scanning direction over the surface area of the
25 photoreceptor 1MK of second process unit 10MK.

Every moment when the laser beams L2 are reflected to a predetermined direction during each scanning, the beams are

detected by a second beam detection means (not shown), provided on a side of the photoreceptor 1MK. A second beam detection signal is then output by the second beam detection means.

Referring again to FIG. 1, the light scanning means 20 is
5 adapted to carry out light scanning by means of one single polygonal unit 23 onto both receptors, one the 1YC photoreceptor for Y and C images included in the first process unit 10YC and the other the 1MK photoreceptor for M and K images included in the second process unit 10MK.

10 As a result, the phase of light scanning in the main scanning direction comes to completely coincide with each other between the 1YC photoreceptor for Y and C images and the 1MK photoreceptor for M and K images.

The notation L1 in the drawing designates the distance
15 between two photoreceptors. This distance, the traveling speed of the intermediate transfer belt 31, and scanning speed in the main scanning direction with the light scanning means 20 (related to the rotational speed of polygonal unit 23) are selected in combination as follows. Namely, the number of beam
20 scanning repetition in the main scanning direction during the time period for the intermediate transfer belt 31 to travel the distance L1 is set to be an integer.

With this setting, disagreement can be alleviated in image overlap or superposition caused by undue shift in the phase of
25 scanning in the main scanning direction between two photoreceptors.

However, even such a setting as above is made to bring the

initiation timings for beam scanning to coincide exactly with each other between two photoreceptors, that is, even after initial positional disagreement of toner images is dissolved between the photoreceptors, possibility still remains of disagreement in
5 image overlap.

This disagreement may be caused by the change in the speed of the surface of intermediate transfer belt 31, in that the position of toner image transfer in relative to the intermediate transfer belt becomes to disagree between the first and second
10 intermediate transfer positions.

In addition, in the case where four process units for Y, M, C, and K images are provided, this disagreement may take place more often between a first color and a fourth color, which are positioned most distant among the four units. In contrast, the
15 disagreement does not take place so often between most neighboring pairs of the units such as, for example, a first color and a second color.

Therefore, it is realized for the printer disclosed herein to be able to effectively suppress the noted disagreement in the
20 position of toner image transfer caused by the change in the speed of the surface of intermediate transfer belt, since it consists of only one pair of the process units 10YC and 10MK neighboring to each other.

In addition, with the construction of the present printer, in
25 which one single polygonal unit 23 is shared by neighboring process units, there alleviated is more complicated structure of the light scanning means 20 otherwise required for the printer

provided with plural polygonal units each for exclusive use.

As described earlier, the printer disclosed herein is adapted to complete the superposing image transfer not during one or less round of surface displacement of intermediate
5 transfer belt 31 but during two rounds of the displacement, and four superposing transfers are in fact carried out during that period.

Namely, the image transfers are carried out more times than the number of round of transfer belt 31 for the printer, in
10 which the transfer operation by two process units are included in addition to that by the rotation of the transfer belt 31. As a result, an increase in printing time can be avoided, which is otherwise required for repeated rotations of as many times as the number of images transferred.

15

FIG. 4 is a diagrammatic block diagram illustrating portions of circuit structure of the printer disclosed herein.

Referring to FIG. 4, connected to a main controller 64 are a data memory means 65 comprising RAM, a time lag
20 measurement means 66, first and second optical write controllers 67 and 68, and a polygon motor controller 29.

In addition, the polygonal motor 23b is connected to the polygonal motor controller 29. Also connected to time lag measurement means 66 are the mark detection means (50 of FIG.
25 1), the first beam detection means (5YC of FIG. 1), and the second beam detection means as base mark detection means for the second process unit (10MK).

These noted units consist of a portion of the light scanning means 20. In other word, the light scanning means 20 is adapted to include the main controller 64 and others in addition to the polygonal unit 23.

5 The main controller 24 is adapted to output start instruction signals in a predetermined timing to the first and second optical write controllers 27 and 28.

On receiving start instruction signals, the first optical write controller 27 instructs to control the drive of the first LD
10 based on image information so as to initiate optical writing onto the photoreceptor 1YC of first process unit 10YC. Similarly, the second optical write controller 28 instructs to control the drive of the second LD based on image information so as to initiate optical writing onto the photoreceptor 1MK of second
15 process unit 10MK YC on receiving the start instruction signals.

The main controller 24 is adapted also to output correction signals in a predetermined timing to the polygonal motor controller 29. The polygonal motor controller 29, in turn, instructs the polygonal motor 23b including a stepping motor to
20 adjust the number of step pulses thereof so as to suitably shifting the rotational phase of the motor 23b based on the correction signals. This also yields the shift of rotational phase for the polygonal motor 23b.

With this structure, the main controller 24 and polygonal
25 motor controller 29 are adapted to serve as deflection angle phase correction means for correcting the phase of the change in beam deflection angle based at least on mark detection, and

beam detection signals.

As described earlier, the mark detection means 50 is adapted to output mark detection signals on detecting a base mark affixed at a predetermined location on the intermediate transfer belt 31.

In the course of two rounds of intermediate transfer belt 31 and superposing transfers of four color images onto the surface of the belt 31, the noted time lag measurement means 66 carries out several measurements as follows.

Namely, a first time lag $dt1$ as the difference between the time Ta when a mark detection signal is detected during the first rotation of the belt 31 and the time when the first mark detection signal from the first beam detection means is firstly detected, and the result from this measurement is output to be stored in the data memory means 65.

Subsequently, a second time lag $dt2$ as the difference between the time Tc when a mark detection signal is detected during the second rotation of the belt 31 and the time when a first beam detection signal is detected firstly after detecting the mark detection signal, and the result from this measurement is output to the main controller 64.

FIG. 5 includes a timing chart illustrating the generation and sequence of several signals in the printer disclosed herein.

As described earlier, the sequential transfer of Y images on first process unit 10YC and M images on second process unit 10MK is carried out during the first rotation of the intermediate

transfer belt 31.

After the rotation of the belt 31 is initiated to carry out the transfer, the base mark onto the transfer belt 31 is detected by the mark detection means 50.

5 Upon outputting a mark detection signal in response to the detection, the time T_a is recognized by the time lag measurement means 66, and a time-keeping for measuring the first time lag dt_1 is initiated. In addition, another time-keeping for measuring a base correction time t_1 stored in
10 the data memory means 65 is also initiated. The base correction time t_1 is set to be equal to, or longer than the time required to shift the phase of the main direction scanning by one cycle by means of the control with the polygon motor controller
29.

15 Incidentally, since the polygonal mirror 23a is of the shape of the regular hexagonal prism, the noted time required to shift the phase of the main direction scanning by one cycle is equal to that for shifting the phase of polygonal mirror rotation by 60 degrees.

20 On outputting a first beam detection signal firstly after the time T_a , another time T_b is recognized by the time lag measurement means 66, and then the time-keeping for measuring the first time lag dt_1 is terminated. And, the result of this time-keeping is stored in the data memory means 65.

25 Subsequently, at the moment when time-keeping for measuring the base correction time t_1 is terminated (or when the time t_1 elapses after T_a), the time T_e (FIG. 5) is recognized by

the time lag measurement means 66.

Thereafter, only at the moment when a first beam
detection signal is output firstly after T_e and when a light beam
is brought to the proper location in the main scanning direction
5 for initiating optical image writing onto the photoreceptor 1YC
for Y and C images, optical image writing steps with the
photoreceptor 1YC are initiated.

Subsequently, by carrying out the sequential transfer of Y
images formed by the first process unit 10YC and M images by
10 the second process unit 10MK, double-color toner images are
formed on the intermediate transfer belt 31.

Thereafter, C images formed by the first process unit 10YC
and K images by the second process unit 10MK are sequentially
transferred onto the double-color toner images.

15 Upon outputting a mark detection signal for the second
round during that period of transfer, the time T_c (FIG. 5) is
recognized by the time lag measurement means 66, and a
time-keeping for measuring the second time lag dt_2 is initiated.
In addition, another time-keeping for the base correction time t_1
20 is also initiated.

On outputting a first beam detection signal firstly after
the time T_c , another time T_d is recognized by the time lag
measurement means 66, and then the time-keeping is
terminated.

25 The main controller 24 then operates to compute a time
difference Δt between the value of the second time lag dt_2 sent
from the time lag measurement means 66 and that of first time

lag dt_1 stored previously in the data memory means 65.

Based on the thus computed time difference Δt , the discrepancy in phase of the scanning in the main scanning direction between the first and second rounds are computed, and
5 the result from this computation is output, as correction signal(s), to the polygon motor controller 29.

The polygon motor controller 29, in turn, operates to vary the number of step pulses applied to the polygon motor 23b so as to correct the phase of rotation for the polygonal mirror 23a.

10 By this correction, the scanning phase in the main scanning direction for the second round is brought to coincide with that for the first round within the period of base correction time t_1 during the second round.

As a result, after the elapse of base correction time t_1
15 during the second round, first detection signals for the second round are adjusted to be sent out repeatedly having the same timing as the first round, as shown in FIG. 5.

As described earlier, only at the moment when a first beam detection signal is output firstly after T_e , optical image writing
20 steps with the photoreceptor 1YC are initiated and similar steps are carried out for the time T_m .

Therefore, the timing for initiating optical image writing steps with the photoreceptor 1YC for Y and C can be synchronized with each other between the first and second
25 rounds of the belt rotation.

As a result, undue mismatch in image superposition in the vertical scanning direction can be obviated, which is caused by

the shift in the phase in the main scanning direction along the rounds of belt rotation. Furthermore, another mismatch in image superposing positions by respective process units in the main scanning direction can also be prevented, which is caused
5 by the variation in the belt surface velocity.

Having described the present disclosure in general, the following examples are provided further to illustrate preferred embodiments of the printer disclosed herein each provided with
10 specific features.

EXAMPLE 1

The time difference Δt between the first time lag dt_1 and second time lag dt_2 also indicates the amount of difference in
15 phase of the rotation of transfer belt in the main scanning direction between the first and second rotations.

Therefore, as long as the time difference Δt is equal to, or less than, a predetermined threshold value, the mismatch in image superposition in the vertical scanning direction can be
20 contained within a tolerance limit in principle, even without correcting the rotation phase during the second rotation in the main scanning direction.

Accordingly, the printer of Example 1 is adapted such that predetermined data for the standard time difference t_s are stored
25 in data memory means 65 in advance and that, in the case where the expression “standard time difference $t_s \geq$ time difference Δt ” holds, the phase correction steps are not carried out prior to the

initiation of the second belt rotation in the main scanning direction.

This adaptation of the printer, however, has to be examined closer, since the noted simple omission of those
5 correcting steps may give rise to color drift (or color mismatch) exceeding a tolerance limit, which is possibly caused depending on the relative magnitude of the two time lags $dt1$ and $dt2$.

The reasons for this possible color mismatch will be described herein below for the case where the standard time
10 difference ts is equal to one quarter of main scanning period T , by way of example.

FIG. 6 includes a timing chart illustrating the sequence of several signals in the case where the expressions "time lag $dt1 <$
time lag $dt2$ " and "time difference $tx <$ time difference ty " both
15 hold.

This time difference tx designates the difference in time between the time Te elapsed by base correction time $t1$ from the mark detection signal during the first round and the time Tf
when a first beam detection signal is output firstly after Te for
20 optical image writing be initiated.

In addition, the time difference ty designates the difference between the time Tm elapsed by base correction time $t1$ from the mark detection signal during the second round and
the time Tn when a first beam detection signal is output firstly
25 after Tm for the optical image writing be initiated.

In the case where the expressions "time lag $dt1 <$ time lag $dt2$ " and "time difference $tx <$ time difference ty " are both

satisfied, the time T_f for the first round of the belt rotation advances with respect to the time T_n for the second round, as shown in FIG. 6.

In this case, although the first line (a line image extending
5 along the main scanning direction) for the second rotation is shifted by one quarter of the dot width backward from that for the first rotation, this magnitude of image mismatch is within the tolerance limit.

In contrast, FIG. 7 includes a timing chart illustrating the
10 sequence of signals in the case where the expressions "time lag $dt_1 < \text{time lag } dt_2$ " and "time difference $tx > \text{time difference } ty$ " both hold.

In similar manner to FIG. 6, the time difference tx designates the difference in time between the time T_e elapsed by
15 base correction time t_1 from the mark detection signal during the first round and the time T_f when a first beam detection signal is output firstly after T_e for optical image writing be initiated, and the time difference ty designates the difference between the time T_m elapsed by base correction time t_1 from the
20 mark detection signal during the second round and the time T_n when a first beam detection signal is output firstly after T_m for the optical image writing be initiated.

In the case where the expressions "time lag $dt_1 < \text{time lag } dt_2$ " and "time difference $tx > \text{time difference } ty$ " are both
25 satisfied, the time T_n for the second round of the belt rotation advances with respect to the time T_f for the first round, as shown in FIG. 7.

Even the time difference Δt remains as one quarter of the main scanning period T in this case, the magnitude of image mismatch is not necessarily contained within one quarter of the dot width, and the color mismatch as large as about one dot width may result depending on the relative magnitude of the two time lags $dt1$ and $dt2$.

It is indicated from the comparison between FIGS. 6 and 7, in order to contain the magnitude of color mismatch within the tolerance limit of one quarter of the dot width in the case of "time lag $dt1 < \text{time lag } dt2$ ", it is necessary to delay the time for initiating optical image writing for the second round is adjusted to be delayed with respect to that for the first round.

Also indicated from FIG. 7 is that, in the case of "time difference $tx > \text{time difference } ty$ ", the color mismatch can be contained within one quarter of the dot width, when the time for initiating optical image writing for the second round is delayed by one period T from the time T_n .

FIG. 8 includes a timing chart illustrating the sequence of signals in the case where the expressions "time lag $dt1 > \text{time lag } dt2$ " and "time difference $tx > \text{time difference } ty$ " both hold.

In this case, the time T_n for the second round of the belt rotation advances with respect to the time T_f for the first round, as shown in the drawing. Although the first line for the second rotation is shifted by one quarter of the dot width backward from that for the first rotation, this magnitude of image mismatch is within the tolerance limit.

FIG. 9 includes a timing chart illustrating the sequence of

signals in the case where the expressions "time lag $dt_1 > \text{time lag } dt_2$ " and "time difference $tx < \text{time difference } ty$ " both hold.

In this case, the time T_f for the first round of the belt rotation advances with respect to the time T_n for the second round as shown in the drawing and the first line for the second rotation is shifted by one quarter of the dot width backward from that for the first rotation.

It is indicated from the comparison between FIGS. 8 and 9, in order to contain the magnitude of color mismatch within the tolerance limit of one quarter of the dot width in the case of "time lag $dt_1 > \text{time lag } dt_2$ ", it is necessary to set forward the time for initiating optical image writing for the second round is adjusted to be delayed with respect to that for the first round.

Also indicated from FIG. 9 is that, in the case of "time difference $tx < \text{time difference } ty$ ", the color mismatch can be contained within one quarter of the dot width, when the time for initiating optical image writing for the second round is advanced by one period T from the time T_n .

Based on the above noted findings, the printer disclosed herein is configured to implement several controls which follow.

That is, the time difference tx , as the difference between the times T_e and T_f is measured by the time lag measurement means 66 during the first round of the belt rotation, and the result from this measurement is stored in the data memory means 65.

Also, based on the result from the measurement of second time lag dt_2 during the second round of the belt rotation, and

the relationship between this result and the base correction time t_1 , the time difference t_y is computed as the difference between the times T_m and T_n .

Since the base correction time t_1 and main scanning period T are herein assumed as constant, the time difference t_y can be calculated from the result of the second time lag dt_2 .

In the case where it is determined, base on the result of comparison of the time difference Δt with standard time difference t_s , that the phase correction steps are not carried out in the main scanning direction, optical image writing steps are initiated at the moment during the second round when a first beam detection signal is detected for the first time after the elapse of a predetermined time from T_c .

Regarding the noted predetermined time, whether its length is set to be equal to, or smaller or larger than, the base correction time t_1 is determined as follows based on the time lags dt_1 and dt_2 , and time differences t_x and t_y .

To be specific, in the case of either " $dt_1 < dt_2$ " and " $t_x < t_y$ ", or " $dt_1 > dt_2$ " and " $t_x > t_y$ ", optical image writing steps are initiated at the moment, during the second round, when a first beam detection signal is detected for the first time after the time T_m (FIGS. 6 and 8).

In contrast, in the case of " $dt_1 < dt_2$ " and " $t_x > t_y$ ", the predetermined time is determined to be "(base correction time t_1) + (main scanning period T)", in which T_n is shifted backward by one cycle, as shown in FIG. 7.

In addition, in the case of " $dt_1 > dt_2$ " and " $t_x < t_y$ ", the

predetermined time is determined to be “(base correction time t_1) – (main scanning period T)”, in which T_n shifted forward by one cycle, as shown in FIG. 9.

By means of the setting described above, the magnitude of
5 image mismatch can be ensured to be contained within the tolerance limit in the case where it is decided that the phase correction steps are not carried out in the main scanning direction.

Namely, again in the case where it is decided that the
10 phase correction steps are not carried out in the main scanning direction, the image mismatch can certainly be contained within the tolerance limit by suitably determining the above noted times, or time parameters, based on the time lags dt_1 and dt_2 , and time differences tx and ty .

15

EXAMPLE 2

In the method for determining several time parameters based on time points T_f and T_e , the time lags dt_1 and dt_2 , and time differences tx and ty , which is utilized in the printer
20 described in Example 1, the method is adopted in which the time parameters such as the time points T_f and T_e , and time differences tx and ty , are firstly measured.

In contrast, the printer mentioned in Example 2 is adapted to utilize another method for determining the noted time
25 parameters, even though the determination of the time points T_f and T_e , and time differences tx and ty , are still involved, which will be described herein below.

Previously illustrated is the case where the expression
“time lag $dt1 < \text{time lag } dt2$ ” holds in reference to FIGS. 6 and 7.

Furthermore, since “time lag $dt1 < \text{time lag } dt2$ ” in FIG. 6,
it is shown that the time T_n for the second round is positioned
5 further back from the time T_c elapsed by “(base correction time
 $t1$) + (time difference tx)”.

As a result, if “(base correction time $t1$) + (time difference
 tx)” is presently defined as an added correction time, $t1'$, proper
timing is achieved also at time T_n , when a first beam detection
10 signal is detected for the first time after the time T_c plus the
added correction time $t1'$ during the second round of the belt
rotation.

In contrast, in the case of “time difference $tx > \text{time}$
difference ty ” as shown in FIG. 7, the time for initiating optical
15 image writing for the second round is preferably delayed by one
period T from the time T_n , as described earlier.

Since “time difference $tx > \text{time difference } ty$ ” in this case,
it is shown that the time is bound to elapse beyond T_n , when
time passes from T_c by the length of the added correction time
20 $t1'$, or $t1$ plus tx .

As a result, the timing, at which a first beam detection
signal is detected for the first time after the time T_c plus the
added correction time $t1'$ (or, $t1 + tx$) during the second round, is
achieved being delayed by one period T from the time T_n .

25 Accordingly, in the case where “time lag $dt1 < \text{time lag}$
 $dt2$ ”, it is preferable for the optical image writing be initiated
at the timing at which a first beam detection signal is detected

for the first time after T_c plus the added correction time t_1' ($t_1 + t_x$) during the second round.

Previously illustrated is the case where the expression “time lag $dt_1 > \text{time lag } dt_2$ ” holds in reference to FIGS. 8 and 9.

5 In both cases, if “(base correction time t_1) + (time difference t_x)” is again defined as an added correction time, t_1' , it is indicated the timing for a first beam detection signal is brought to be synchronized with the timing which is earlier by the time difference Δt from the time T_c plus the added correction
10 time t_1' (or, $t_1 + t_x$) during the second round of the belt rotation.

Also indicated is that, when optical image writing for the second round is initiated at the above noted timing, the image mismatch can be contained within the tolerance limit.

Accordingly, in the case where “time lag $dt_1 > \text{time lag } dt_2$ ”, it is preferable for the optical image writing during the
15 second round of belt rotation be initiated at the timing which is earlier by the time difference Δt from the time T_c plus the added correction time t_1' (or, $t_1 + t_x$).

Based on the above noted findings, the present printer is
20 configured to determine the timing of optical image writing during the second round of belt rotation as follows.

That is, the added correction time t_1' (or, $t_1 + t_x$) is firstly measured during the first round of the belt rotation, and then a time-keeping step is initiated at T_c for the second round.

25 Subsequently, as soon as the time difference Δt based on time lag dt_2 is obtained, “(added correction time t_1') - (time difference Δt)” is computed, which is successively compared with

time currently counted. Thereafter, just prior to the moment when the time currently counted reach the computed result of " $t1' \cdot \Delta t$ " (the computed result $- T/10$, for example), the time-keeping is terminated.

5 Therefore, in the case where it is decided that the phase correction is not carried out in the main scanning direction, in a similar manner to Example 1, the image mismatch can be contained within the tolerance limit by suitably determining the timing for initiating the optical image writing as described
10 above.

 Namely, again in the case where it is decided that the phase correction steps are not carried out in the main scanning direction, the image mismatch can be contained within the tolerance limit by suitably determining the above noted times, or
15 time parameters, based on the time lags $dt1$ and $dt2$, and added correction time $t1'$.

EXAMPLE 3

 The printer disclosed in Example 3 is provided with a
20 plurality of base marks equally spaced with a predetermined pitch there between each affixed onto one of the circumferential edges of the intermediate transfer belt 31 in the direction of its endless rotation.

 The noted predetermined pitch is taken as "(distance
25 between process units $L1$) $-$ (distance $L2$)", where $L2$ is the distance covered by the displacement of the intermediate transfer belt 31 over the base correction time $t1$.

Owing to such structure and to relatively small size of toner images formed, it is well assumed that optical image writing onto 1YC photoreceptor for Y and C images, which is previously initiated based on a mark detection signal, is
5 completed by the time a next mark detection signal is detected.

Under such conditions, it is also assumed that Y or C toner images on the 1YC photoreceptor for Y and C images are not disturbed, even if the phase of the main direction scanning is shifted by controlling the drive of polygonal motor
10 23b at the time the mark detection signal is detected.

In addition, when correction steps for shifting the phase of the main direction scanning by one cycle is initiated at the time the mark detection signal is detected, the noted control can be completed by the time when the moment arrives for the
15 succeeding optical image writing onto 1MK photoreceptor for M and K images have to be initiated.

Therefore, even in the case where a relatively large change arises in speed of the intermediate transfer belt caused by belt slippage, for example, the disagreement in image superposition
20 caused by the slippage can be suppressed without disturbing the Y and C toner images by initiating the correction of the phase in the main direction scanning at the time the slippage arises.

Accordingly, the printer disclosed herein is configured to be capable of obviating the disagreement in image superposition
25 even in the case where a relatively large change arises in speed of the intermediate transfer belt caused by belt slippage between the neighboring photoreceptors.

To be specific, if optical image writing onto 1YC photoreceptor for Y and C images is completed at time T_g , which is one rotation cycle after the time T_a for the first rotation of the belt, as illustrated in FIG. 10, time-keeping steps are carried out
5 for measuring a time lag dt_3 between T_g and the time when a second beam detection signal is detected for the first time after T_g .

In the case where no major belt velocity change caused by belt slippage is caused during T_a and the time mentioned just
10 above, the time lags dt_3 and dt_1 are equal to each other. In contrast, there gives rise to a difference between the two, when the belt slippage has been caused.

When this difference exceeds a predetermined threshold, the drive control of polygonal motor 23a is carried out to adjust
15 the phase in the main scanning direction and to be brought into coincidence with the phase prior to the belt slippage.

Thus, the timing for initiating optical image writing onto 1YC photoreceptor for Y and C images during the first round of belt rotation is synchronized with that onto 1MK photoreceptor
20 for Y and C images, in relative manner as shown in FIG. 10, that is, each resulting the same timing at (base correction time t_1) plus (time difference t_x).

For the second round of the rotation, steps for correcting the phase of the main direction scanning to coincide with that
25 during the first round of belt rotation are carried out prior to optical image writing onto 1YC photoreceptor for Y and C images.

In addition, when optical image writing onto 1YC photoreceptor for Y and C images is completed at time T_h when a succeeding beam detection signal is detected for the first time after T_c , time-keeping steps are carried out for measuring a time lag dt_4 between T_h and the time when a second beam detection signal is detected for the first time after T_h .

Thereafter, when the difference between the time lags dt_2 and dt_4 exceeds a predetermined threshold, the drive control of polygonal motor 23a is carried out to adjust the phase in the main scanning direction and to be brought into coincidence with the phase prior to the belt slippage.

As a result, the timing of initiating image writing for all of the first, second, third, and fourth colors, is brought to be synchronized with each other at the timing of (base correction time t_1) plus (time difference tx) in relative manner as shown in the drawing.

EXAMPLE 4

The printer disclosed in Example 4 is also configured to be capable of obviating the disagreement in image superposition even in the case where a relatively large change arises in speed of the intermediate transfer belt caused by belt slippage between the neighboring photoreceptors.

In place of the plurality of base marks in the previous printer, however, only one base mark are affixed to the intermediate transfer belt and two mark detection means are provided. One of the mark detection units is placed at the same

location as the first mark detection means of FIG. 1, and the second mark detection means is placed between 1YC photoreceptor for Y and C images and 1MK photoreceptor for M and K images.

5 In addition, the distance between these mark detection means is adjusted to be the “(distance between process units L1) – (distance L2)”.

 Therefore, the time difference between the timings of mark detection by the mark detection means comes to be equal to that
10 between a first base mark and next succeeding base mark, described earlier on the printer of Example 3.

 In this structure, there defined are the time T_i as the timing when a mark detection signal is detected after T_a , as a second mark detection signal, by the second mark detection
15 means; the time lag dt_5 as the time when a second mark detection signal is detected for the first time after T_i ; the time T_j as the timing when a second mark detection signal is detected after T_c by the second mark detection means; and the time lag dt_6 as the time when a second mark detection signal is detected
20 for the first time after T_c .

 By utilizing the noted time parameters, the parameters of FIG. 10 such as the times T_g and T_h , and time lags dt_3 and dt_4 are now replaced with the above noted parameters such as the times T_i and T_j , and time lags dt_5 and dt_6 , respectively, whereby
25 the disagreement in image superposition can be suppressed even in the case where a relatively large change in speed of the intermediate transfer belt is caused.

EXAMPLE 5

The printer disclosed in Example 5 is configured to suitably be operated according to specific image information, in
5 that the images to be formed are of double-color, and are able to be formed by superposing Y or C images which can be formed by the first process unit 10YC, and M or K images which can be formed by the second process unit 10MK.

In such a case, the printer can operate to form resultant
10 double-color images without rotating twice the intermediate transfer belt 31.

However, this printer is configured to leave the development means enabled (or on standby) such as 3Y for Y images and 3M for M images included in first and second process
15 units 10YC and 10MK, respectively.

In the printer operation as it is, a second rotation of the belt 31 is needed when the second color of the double-color is of either M or K.

Therefore, an improvement can be provided in such a case
20 as above with the second color of either M or K, such that appropriate development means 3M or 3K included in the process unit 10YC or 10MK, respectively, are enabled by the aforementioned development shifting means in place of the development means 3Y or 3M included in the process unit 10YC
25 or 10MK.

With this improved structure, a prolonged image formation period can be alleviated, which is otherwise caused by the

previous structure enabling the development means always in a preset color sequence and often necessitating the second rotation to form the images of arbitrarily selected double colors, as mentioned earlier.

5

The apparatuses and process steps set forth in the present description may therefore be implemented using suitable host computers and terminals incorporating appropriate processors programmed according to the teachings disclosed herein, as will
10 be appreciated to those skilled in the relevant arts.

Therefore, the present disclosure also includes a computer-based product which may be hosted on a storage medium and include instructions which can be used to program a processor to perform a process in accordance with the present
15 disclosure. The storage medium can include, but is not limited to, any type of disk including floppy disks, optical disks, CD-ROMs, magneto-optical disks, ROMs, RAMs, EPROMs, EEPROMs, flash memory, magnetic or optical cards, or any type of media suitable for storing electronic instructions.

20

It is apparent from the above description including example, the printer disclosed herein has several advantages over similar apparatuses previously known.

For example, the first and second process units included in
25 the printer constitute a pair neighboring with each other, each comprising two visible image forming means which are each in the relationship neighboring with each other.

In this printer, after forming a double-color image by sequentially transferring to superpose Y and M toner images each formed by the first and second process units onto the surface of intermediate transfer belt during a first round of rotation of the transfer belt, a quadruple-color image is formed by sequentially transferring to superpose C and K toner images each formed by the first and second process units onto the double-color image during the second round of rotation of intermediate transfer belt.

In addition, the light scanning means 20 is configured, after storing the time lag $dt1$ during a first rotation of intermediate transfer belt, to measure the time lag $dt2$ during the second rotation of intermediate transfer belt, and to correct the phase based on time lag $dt2$ and time lag $dt1$ previously stored.

As a result of the noted construction of the printer, by correcting the phase of rotation in the main direction scanning during each round of the rotation based on time lags $dt1$ and $dt2$, the disagreement in images through quadruple superposition can be obviated.

In addition, the light scanning means 20 included in the apparatus is configured to initiate optical image writing for a first round of rotation of intermediate transfer belt onto the photoreceptor 1YC for Y and C images based on the first mark detection signal detected firstly after the time T_e .

Furthermore, by correcting the phase, during the period between time T_c and the time T_c elapsed by base correction time

t1, based on time lag dt2 and time lag dt1, the light scanning means is adapted to initiate optical image writing for a second round of rotation of intermediate transfer belt onto the photoreceptor 1YC for Y and C images.

5 As a result, by initiating optical image writing after the time elapsed by t1 for each round of rotation, the correction of the phase in the main direction scanning is secured for the second round of rotation prior to initiating optical image writing onto the photoreceptor 1YC for Y and C images.

10

Although characteristic features and advantages of the present printer have been described earlier, they are summarized as follows.

15 The printer disclosed herein is adapted not to carry out the phase correction steps in the case of "standard time difference $t_s \geq$ time difference Δt ". With this construction the mismatch in image superposition in the vertical scanning direction can be contained within a tolerance limit, and the deterioration of the polygonal motor unit is prevented which
20 is otherwise caused by the application of step pulses for shifting the rotational phase of the motor based on correction signals.

 In addition, the printer is adapted, in the case where it is decided that the correction of the phase is not implemented, to initiate optical image writing for a second round of belt rotation
25 based on the time when the standard angle detection signal is detected firstly after a time elapsed by a predetermined time from Tc, and to determine the predetermined time in comparison

with the base correction time t_1 based on at least the times T_f and T_e , base correction time t_1 , time lags dt_1 and dt_2 .

With this construction the image mismatch can be contained within the tolerance limit.

5 To be specific, the printer is adapted to determine the predetermined time based on the time difference t_x between the time T_e and the time T_f , and magnitude relation of the time lags dt_1 and dt_2 . Proper timing for initiating optical image writing for a second round of belt rotation can therefore be determined.

10 Alternatively, the printer is adapted to determine the predetermined time based on at least magnitude relation of the time lags dt_1 and lag dt_2 , and the added correction time t_1' (or $t_1 + t_x$). Proper timing for initiating optical image writing for a second round of belt rotation can therefore be determined.

15 Still in addition, the printer is further provided with plural base marks equally spaced with a predetermined pitch there between each affixed onto the intermediate transfer belt member in the direction of endless rotation.

 In the case where optical image writing onto 1YC
20 photoreceptor for a first round of belt rotation is completed at the time T_g when a predetermined number of the mark detection signals are detected after the time T_a , this printer is adapted to correct the phase, during the period between the time T_g and the time after time T_g elapsed by the base correction time t_1 , based
25 on the time lag dt_3 and the time lag dt_1 , and to initiate optical image writing onto 1MK photoreceptor for the first round of belt rotation.

As a result, the disagreement in image superposition caused by the slippage can be suppressed even in the case where a relatively large change arises in speed of the intermediate transfer belt caused by belt slippage between the pair of the neighboring photoreceptor during the first round of belt rotation.

Alternatively, in the case where optical image writing onto 1YC photoreceptor for a second round of belt rotation is completed at the time T_h , this printer is adapted to correct the phase, during the period between the time T_h and the time after time T_h elapsed by the base correction time t_1 , based on the time lag dt_4 and the time lag dt_1 , and to initiate optical image writing onto 1MK photoreceptor for the second round of belt rotation.

As a result, the disagreement in image superposition caused by the slippage can be suppressed even in the case where a relatively large change arises in speed of the intermediate transfer belt caused by belt slippage between the pair of the neighboring photoreceptor during the second round of belt rotation.

In addition, the printer is further provided with a first mark detection means as the mark detection means and a second mark detection means.

In the case where optical image writing onto 1YC photoreceptor for a first round of belt rotation is already completed at the time T_i when a mark detection signal is detected by the second mark detection means after the time T_a when a previous mark detection signal is detected by the first

mark detection means, the light scanning means is adapted to correct the phase, during the period between the time T_i and the time after time T_i elapsed by the base correction time t_1 , based on the time lag dt_5 and the time lag dt_1 , and to initiate optical
5 image writing onto 1MK photoreceptor for the first round of belt rotation.

As a result, the disagreement in image superposition caused by the slippage can be suppressed even in the case where a relatively large change arises in speed of the intermediate
10 transfer belt caused by belt slippage between the pair of the neighboring photoreceptor during the first round of belt rotation.

Alternatively, in the case where optical image writing onto 1YC photoreceptor for a first round of belt rotation is already completed at the time T_i when a mark detection signal is
15 detected by the second mark detection means after the time T_c when a previous mark detection signal is detected by the first mark detection means, the light scanning means is adapted to correct the phase, during the period between the time T_j and the time after time T_j elapsed by the base correction time t_1 , based
20 on the time lag dt_6 and the time lag dt_2 , and to initiate optical image writing onto 1MK photoreceptor for the second round of belt rotation.

As a result, the disagreement in image superposition caused by the slippage can be suppressed even in the case where
25 a relatively large change arises in speed of the intermediate transfer belt caused by belt slippage between the pair of the neighboring photoreceptor during the second round of belt

rotation.

In addition, the printer is adapted in the case where the image information is of double-color images which can be formed by superposing first color images formed by the first process unit
5 10YC and second color images formed by the second process unit 10MK, to initiate optical image writing onto 1YC photoreceptor.

In such a case, the printer can operate to form resultant double-color images without rotating twice the intermediate transfer belt.

10 Alternatively, in the case where the double-color images can be formed of the first color which can be developed anyone of the plurality of development means included in the first process unit 10YC and of the second color which can be developed anyone of the plurality of development means included in the second
15 process unit 10MK, the first and second process units are each adapted to enable the first color and the second color, respectively, by selectively enabling one of the plurality of development means included in each of the first and second process units by means of the development effecting means.

20 Thus, there obviated with the present apparatus are the shear of superposed images in the vertical scanning direction, prolonged image forming periods resulted from a large number of rotation of intermediate transfer member, and undue complication in the structure of light beam scanning means
25 caused by incorporating plural light deflecting means for exclusive use for each visible image forming units.

Obviously, additional modifications and variations of the present invention are possible in light of the above teachings. It is therefore to be understood that within the scope of the appended claims, the invention may be practiced otherwise than
5 as specifically described herein.

This document claims priority and contains subject matter related to Japanese Patent Application No. 2003-78943, filed with the Japanese Patent Office on March 20, 2003, the entire
10 contents of which are hereby incorporated by reference.